

# Chaotic Circuits – An Introduction

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Bharathwaj “Bart” Muthuswamy

[muthuswamy@msoe.edu](mailto:muthuswamy@msoe.edu)

Assistant Professor of Electrical Engineering

Milwaukee School of Engineering

BS (2002), MS (2005), PhD (2009) from Cal (University of California, Berkeley)

Advisor: Dr. Leon O Chua, co-advisor: Dr. Pravin Varaiya

<http://www.harpgroup.org/muthuswamy>

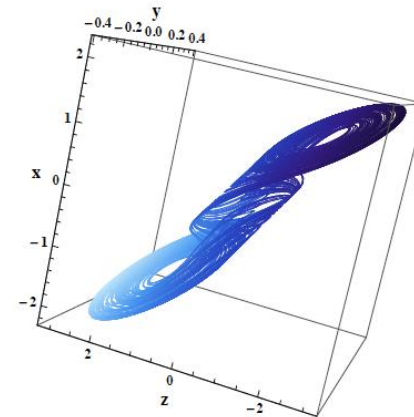
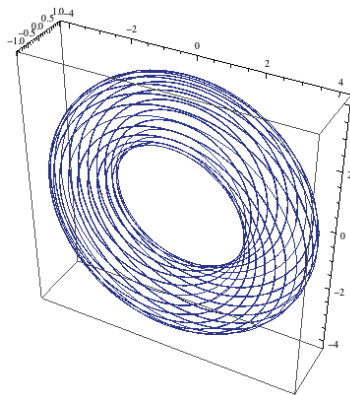
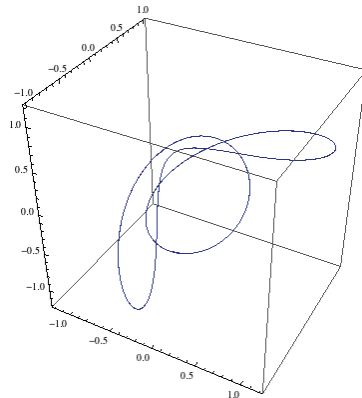
# What do I work on?

## Nonlinear Dynamical Systems and Embedded Systems

- Applications and Mathematical properties of the LCM chaotic circuit
  - Number Theory (Bharathidasan University, Tiruchy, India)
  - Local activity (University of Western Australia, Perth, Australia)
  - Flow manifolds (I.U.T. de Toulon, La Garde Cedex, France)
- Applications of Chaotic Delay Differential Equations using Field Programmable Gate Arrays (University Putra Malaysia, Malaysia )
- Pattern Recognition Using Cellular Neural Networks (University of California, Berkeley, USA)
- Gait generation using nonlinear dynamics for children with Cerebral Palsy\* (Medical College of Wisconsin, Wauwutosa, USA)
- Memristive behavior in superconductors (University of California, Berkeley, USA; Vellore Institute of Technology, Vellore, India)

## Education

- edX program (University of California, Berkeley; Massachusetts Institute of Technology; Harvard University, USA)
- Nonlinear Dynamics at the undergraduate level (with folks from all over the world ☺ )



This talk : LCM Chaotic Circuit

# Outline

## I. Prerequisites for understanding this talk:

1. First course in circuit theory\*
2. First course in differential equations

## II. Introduction

1. Fundamental Circuit Theory [2] [3]
2. Static vs. Dynamical systems

## III. Steady-state Solutions of Differential equations

1. Simple Harmonic Oscillator
2. Quasi-periodicity
3. Chaos [1] [5] [10]

## IV. Physical Realization - electronic circuits

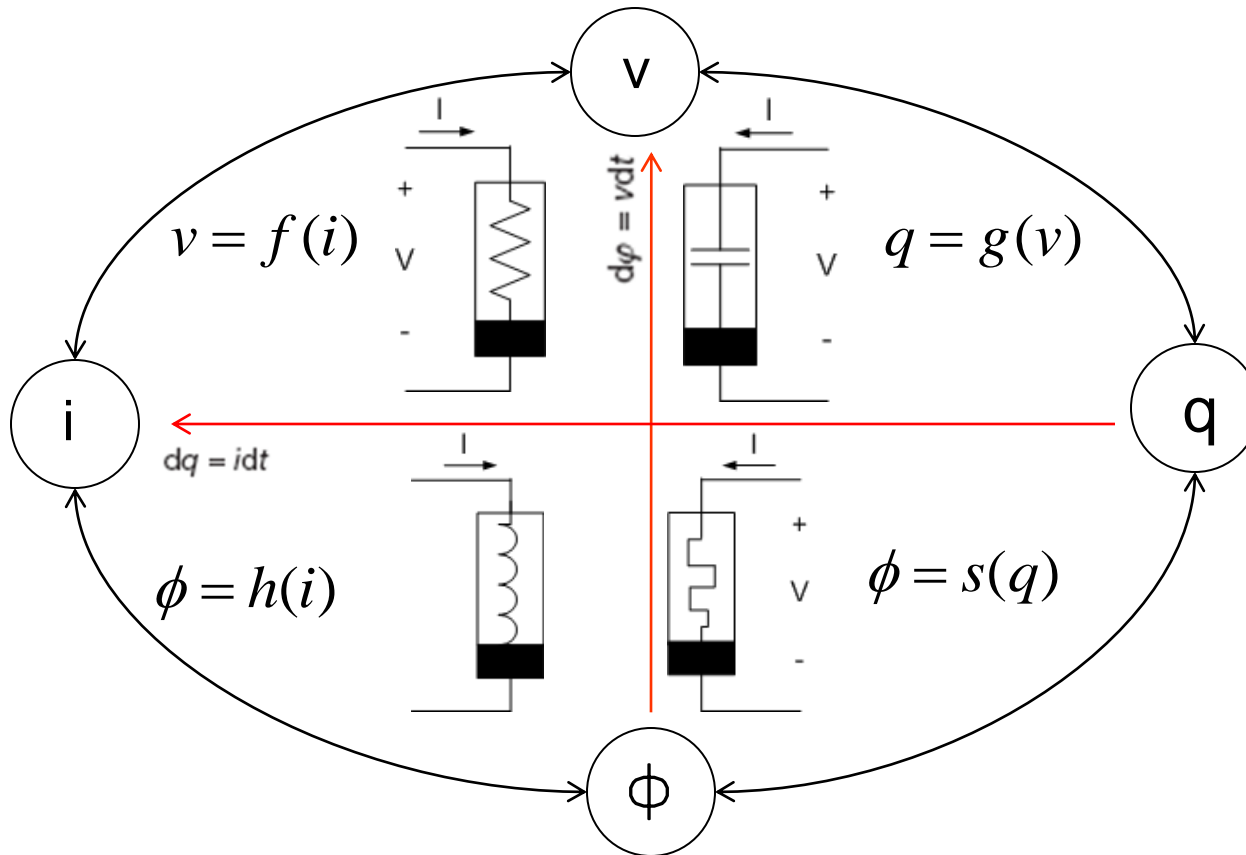
1. LCR circuit
2. LCM circuit [7]
3. Mathematical Property of chaos - The “Dimension” of a chaotic attractor [9]
4. Mathematical Property of chaos - The Frequency Spectrum [7]

## V. An Application of Chaos : Human arrhythmia control [4]

## VI. References

# Introduction :

## Fundamental Circuit Theory [2] [3]



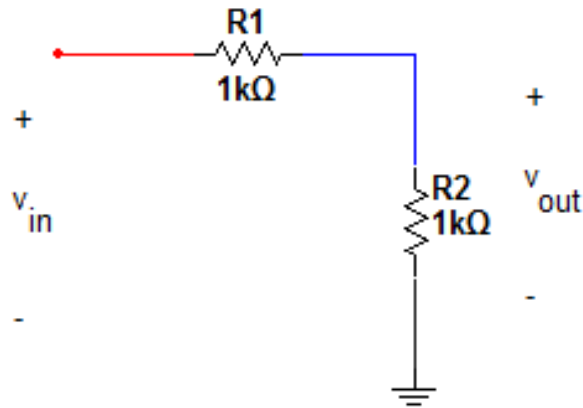
Memristors were first postulated by Leon. O Chua in 1971 [2]

# Introduction :

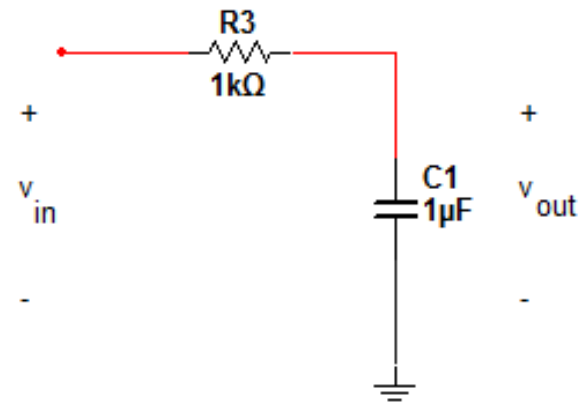
## Static vs. Dynamical Systems

### 1. Mathematical definition of a system

$$y(t) = S(x)(t) \quad y, x : \mathbb{R} \rightarrow \mathbb{R}, t \in \mathbb{R} \quad (1)$$



$$v_{out}(t) = \frac{R2}{R1 + R2} v_{in}(t) \quad (2)$$



$$R3C1 \frac{dv_{out}}{dt} + v_{out} = v_{in} \quad (3)$$

$$v_{out}(t) = v_{out}(0)e^{-t/(R3C1)} + \frac{1}{R3C1} \int_0^t e^{-\frac{t-\tau}{R3C1}} v_{in}(\tau) d\tau \quad (4)$$

### 2. Concept of a linear time-invariant system

### 3. Various system behaviors: stable, unstable

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# Simple Harmonic Oscillator

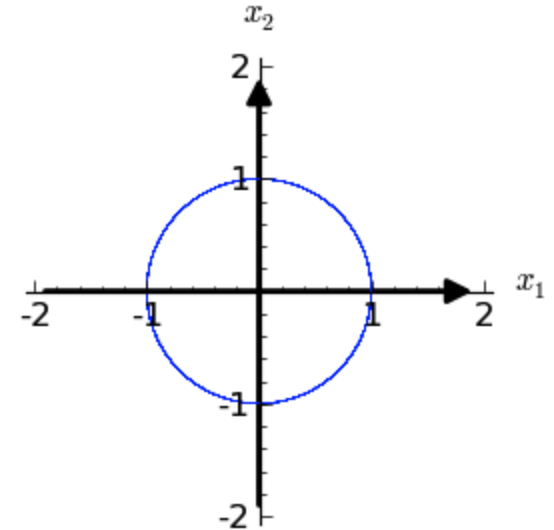
$$\ddot{x} + x = 0 \quad (5)$$

$$\downarrow (x_1 \triangleq x, x_2 = \dot{x})$$

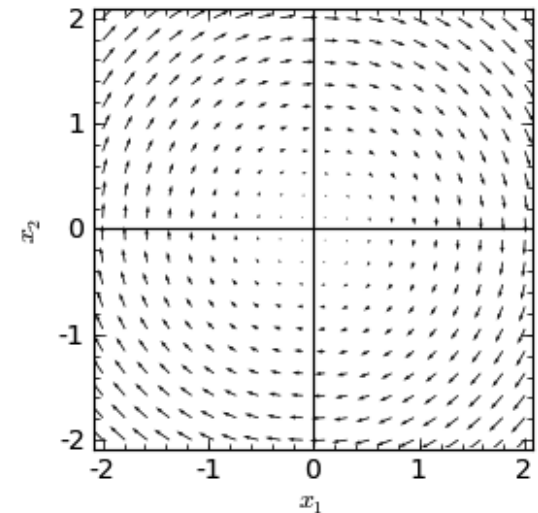
$$\dot{x}_1 = x_2 \quad (6)$$

$$\dot{x}_2 = -x_1$$

Phase portrait:



Vector field:



Plots were obtained using SAGE:

<http://www.sagemath.org/index.html>

# Quasi-Periodicity

After stable, unstable and oscillatory behavior, we have quasi-periodicity [6]

$$\ddot{x} - \left( \lambda + z + x^2 - \frac{1}{2} x^4 \right) \dot{x} + \omega_0^2 x = 0 \quad (7)$$

$$\dot{z} = \mu - x^2$$

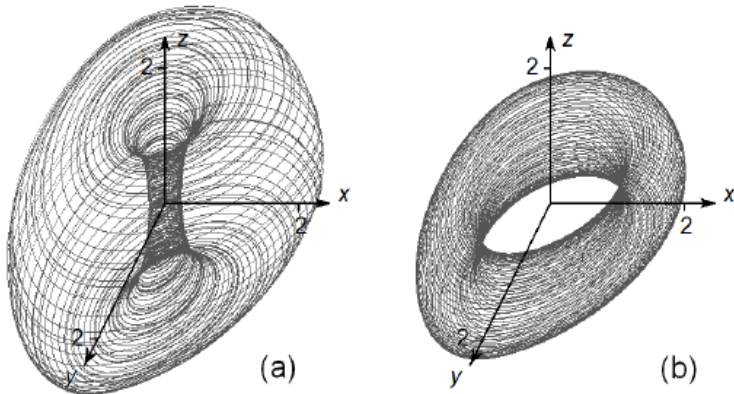


Figure 2. Portraits of attractor in the three-dimensional phase space of variables  $(x, y = \dot{x}/\omega_0, z)$  for the model (1) with  $\lambda=0, \omega_0 = 2\pi$  at  $\mu=0.5$  (a) and  $\mu=0.9$  (b)

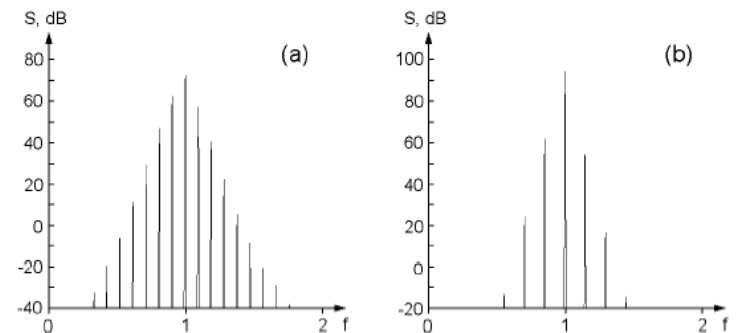


Figure 3. Fourier spectra of oscillations of the variable  $x$  on the attractor for the model (1) with  $\lambda=0, \omega_0 = 2\pi$  at  $\mu=0.5$  (a) and  $\mu=0.9$  (b)



# Chaotic Systems [1] [5] [10]

- “Birth” of Chaos: Lorenz Attractor [8]
  - Edward Lorenz introduced the following nonlinear system of differential equations as a crude model of weather in 1963:

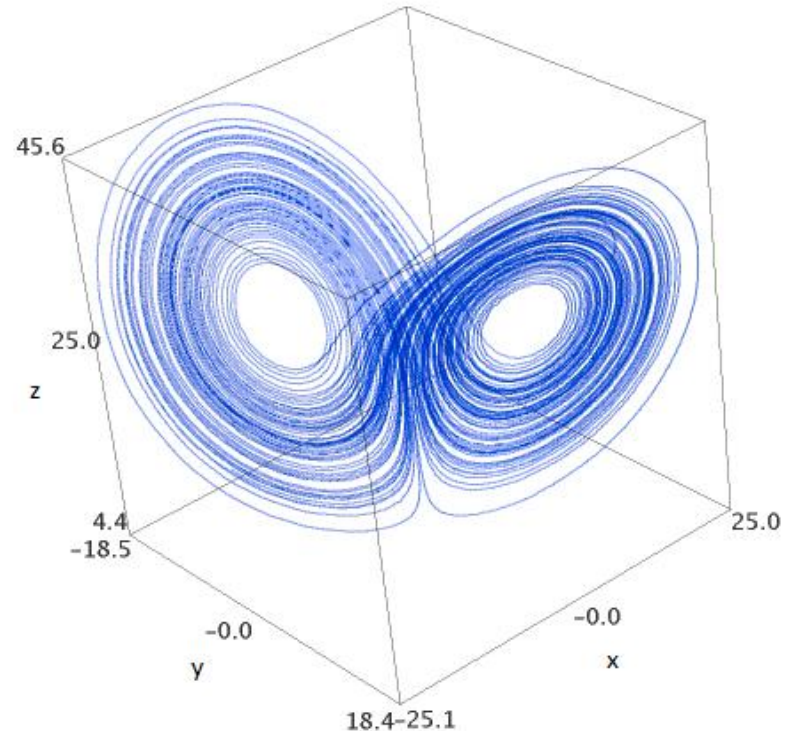
$$\begin{aligned}\dot{x} &= -\sigma \cdot x + \sigma \cdot y \\ \dot{y} &= \rho \cdot x - y - x \cdot z \\ \dot{z} &= -\beta \cdot z + x \cdot y\end{aligned}\quad (8)$$

Parameters:  $\sigma = 10, \rho = 28, \beta = \frac{8}{3}$

ICs:  $x_0 = 10, y_0 = 20, z_0 = 30,$

Simulation time: 100 seconds

- Lorenz discovered that model dynamics were extremely sensitive to initial conditions and the trajectories were aperiodic but bounded.
- But, does chaos exist *physically*? Answer is: YES.



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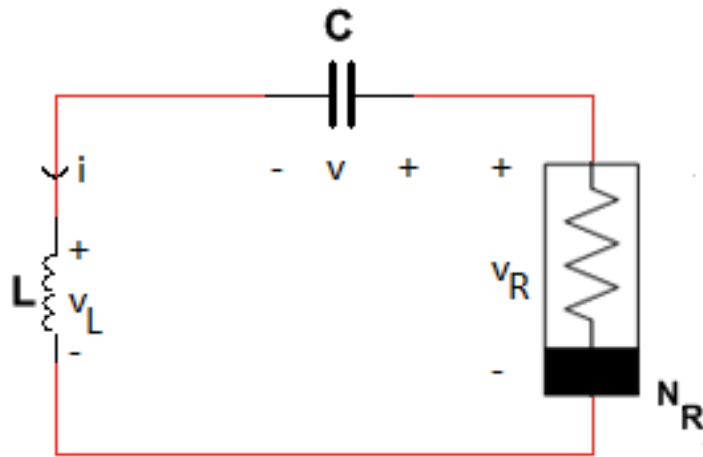
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# LCR Circuit - Derivation of Circuit Equations



Circuit equations:

$$\dot{v} = \frac{i}{C} \quad (9)$$

$$i' = \frac{v_L}{L} \quad (10)$$

$$v_R = -iR \quad (11)$$

ONE differential equation – start with KVL:  $v_R - v - v_L = 0 \quad (12)$

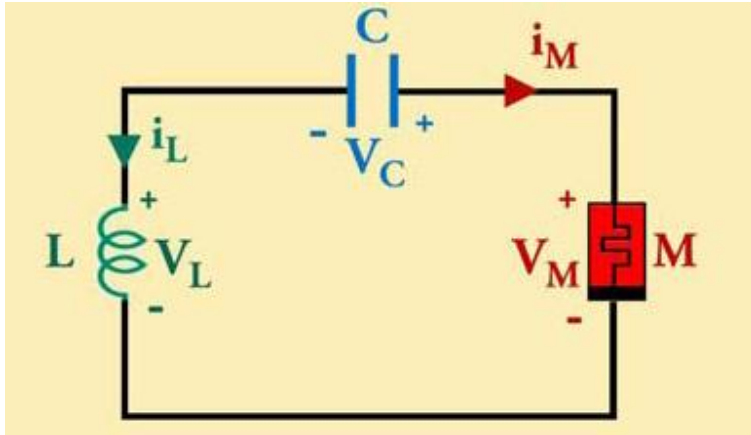
↓ ?

$$i'R + \frac{i}{C} + Li'' = 0 \quad (13)$$

# LCM Circuit - Derivation of Circuit Equations [7]

$$v_M \triangleq R(z, i_M) i_M$$

$$\dot{z} = f(z, i_M)$$



Circuit equations:

$$\dot{v}_C = \frac{i_L}{C} \quad \xrightarrow{x \triangleq v_C, y \triangleq i_L} \quad \dot{x} = \frac{y}{C}$$

$$i'_L = \frac{-1}{L} (v_C + R(z, i_L) i_L) \quad \dot{y} = \frac{-1}{L} (x + R(z, y) y) \quad (14)$$

$$\dot{z} \triangleq f(z, i_L) \quad \dot{z} = f(z, y)$$

System equations:

Specifically:

$$\dot{x} = \frac{y}{C}$$

$$\dot{y} = \frac{-1}{L} (x + \beta(z^2 - 1)y) \quad (15)$$

$$\dot{z} = -y - \alpha z + yz$$

Parameters:

$$\xrightarrow{\hspace{2cm}}$$

$$C = 1, L = 3$$

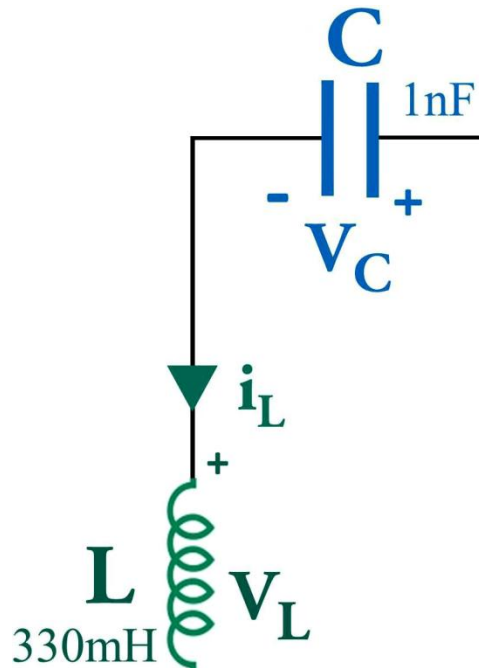
$$\beta = \frac{3}{2}, \alpha = \frac{3}{5}$$

$$\dot{x} = y$$

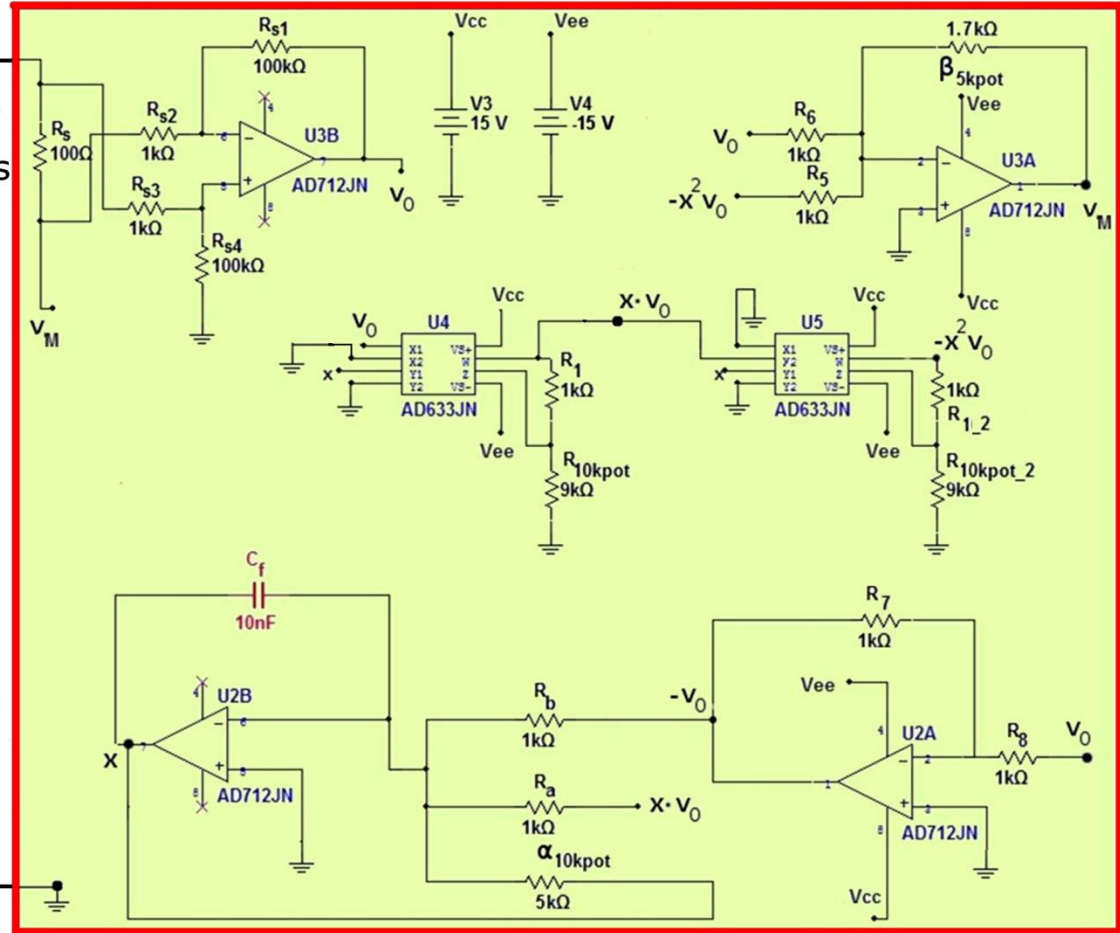
$$\dot{y} = \frac{-x}{3} - \frac{z^2 y}{2} + \frac{y}{2} \quad (16)$$

$$\dot{z} = -y - 0.6z + yz$$

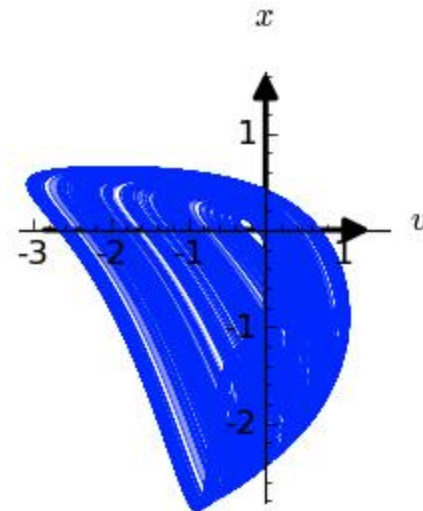
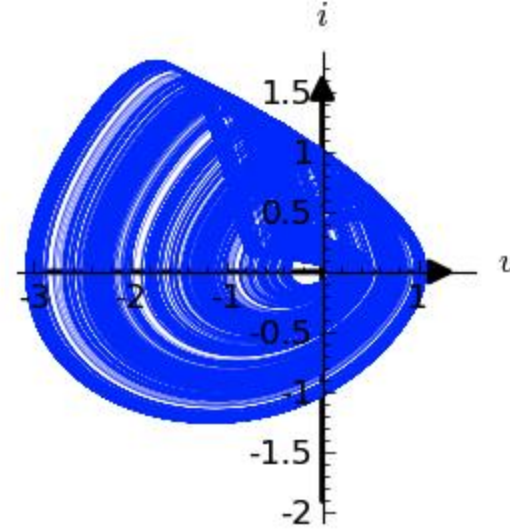
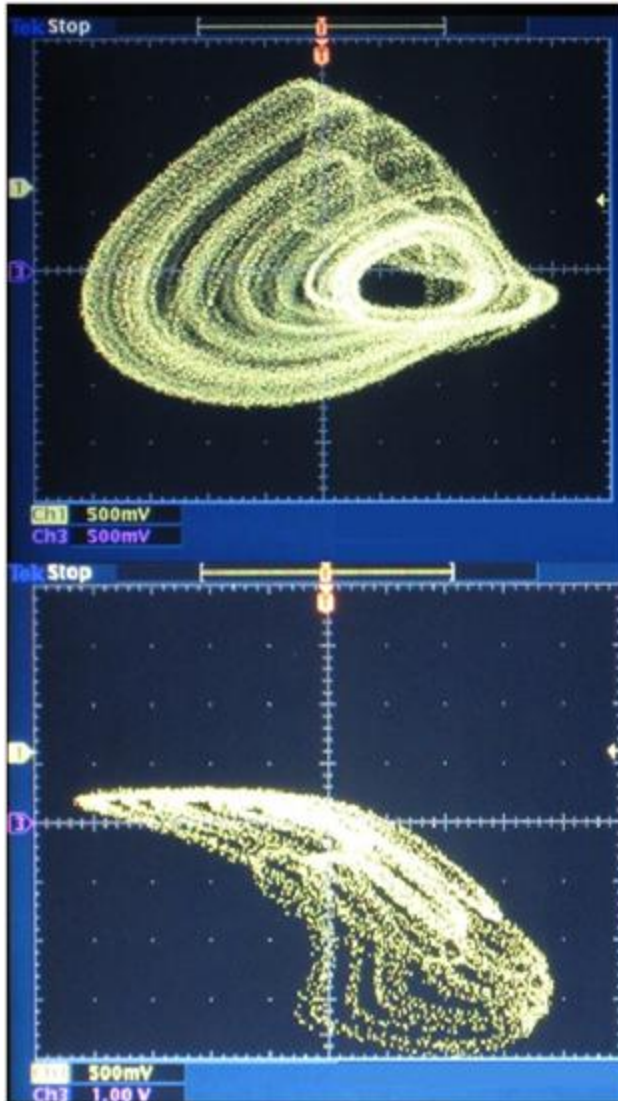
# LCM Circuit - Physical Realization [7]



**Memristor**



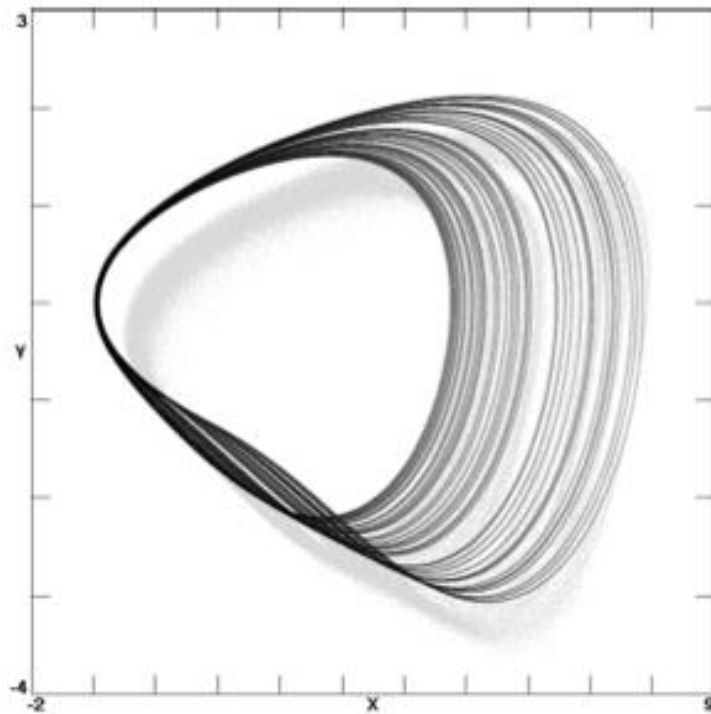
# Attractors from the Circuit [7]



# Mathematical Property of Chaos - “Dimension” of a Chaotic Attractor [9]

$$\ddot{x} + \alpha \dot{x} + x + f(\dot{x}) = 0 \quad (17)$$

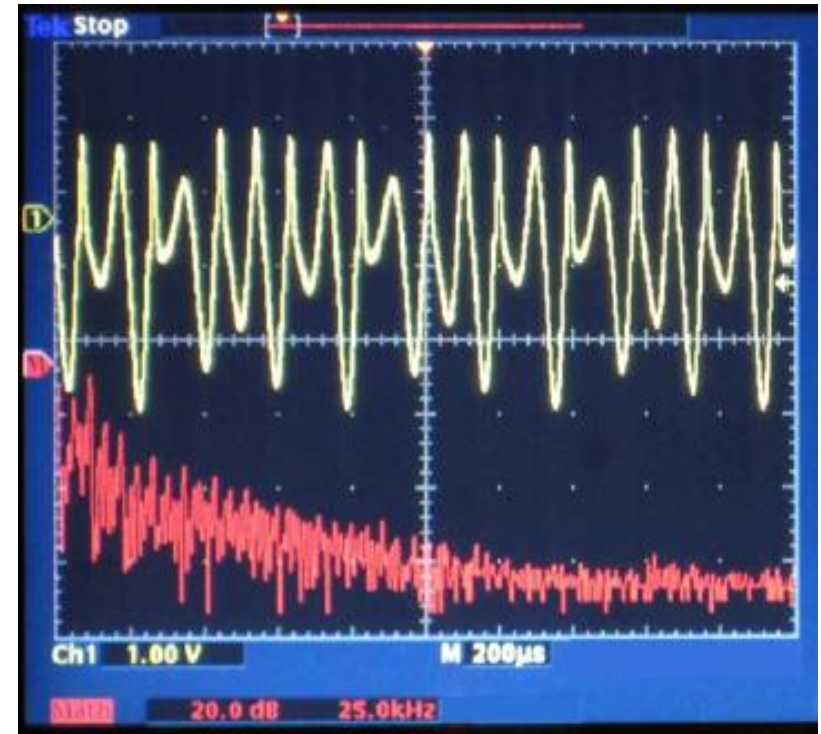
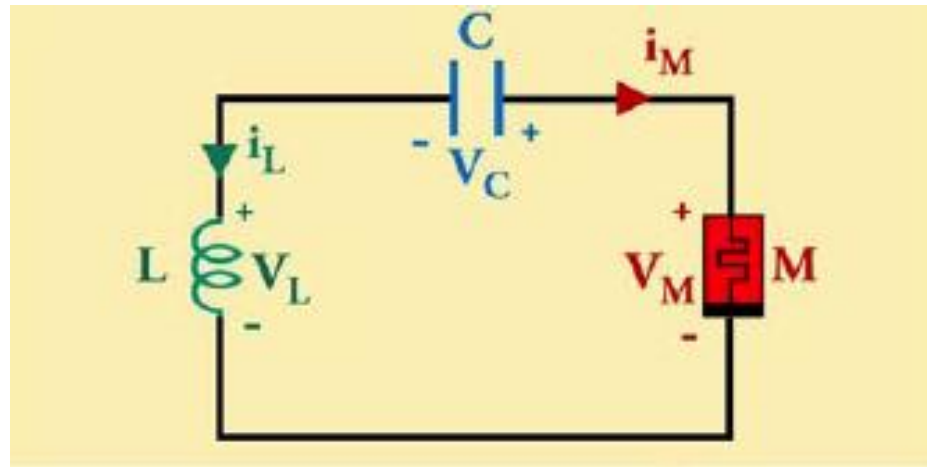
$$\alpha = 2.02, f(\dot{x}) = -\dot{x}^2, \text{i.c.}=(5,2,0)$$



$$\lambda=(0.0486,0,-2.0686)$$

$$D_{KY} = 2 + \frac{0.0486 + 0}{|-2.0686|} \approx 2.02349$$

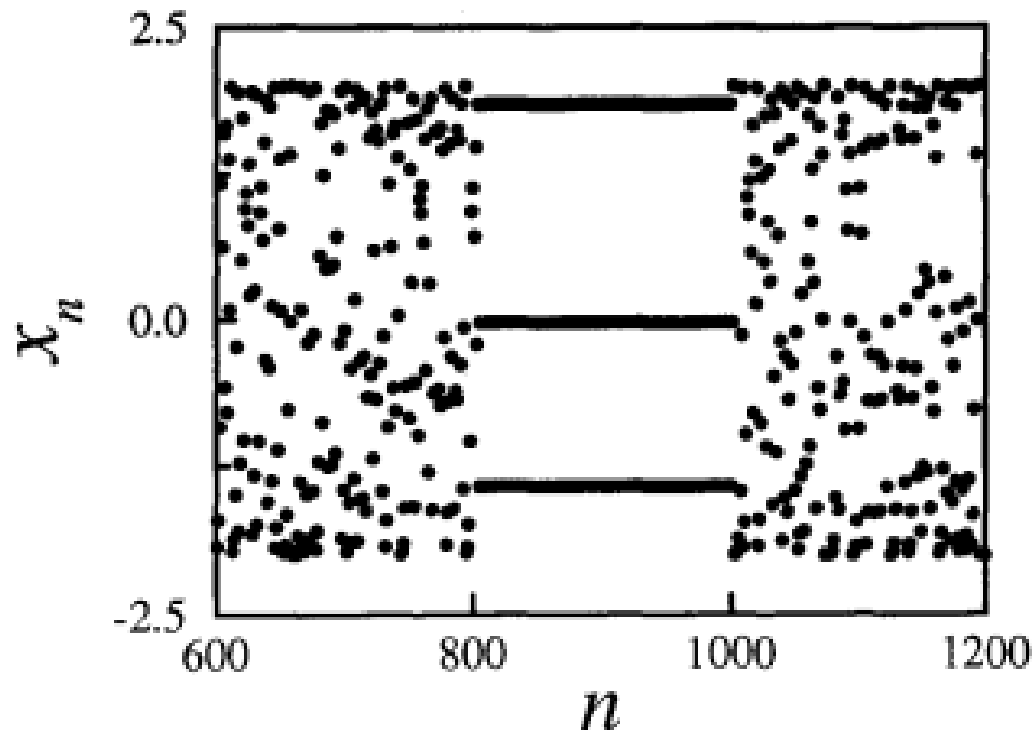
# Mathematical Property of Chaos - The Frequency Spectrum [7]





# An Application of Chaos: Human arrhythmia control [4]

1. Arrhythmia = “not in rhythm” = bad



# References

1. Alligood, K. T., Sauer, T. and Yorke, J. A. *Chaos: An Introduction to Dynamical Systems*. Springer, 1997.
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## Questions?

Now....Computer Science ☺ - SICP!