## Chaos In Memristive Model of Josephson Junction

Bharathwaj Muthuswamy, Jovan Jevtic, Fatma Yildrim Dalkiran and Clint Sprott Research Progress Report for Week of Jan. 2nd 2012

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In this work, we propose to analyze the model shown in Figure 1 for the Josephson junction. The capacitor C models junction capacitance, the flux-controlled memristor M models the interference among quasi-particle pairs, the nonlinear inductor L is the standard junction current<sup>1</sup>. The shunt composed of the linear resistor R and linear inductor L is used in high frequency applications. This inductive shunt is part of the more accurate RCLSJ model of the Josephson junction [3].



Figure 1: A proposed model for the Josephson junction. Passive sign convention is used for all current-voltage relationships. Current through the memristor is given by  $G\cos(k_0\phi)$  and current through the nonlinear inductor is given by  $I_0\sin(\phi)$ .  $\phi = \frac{h}{4\pi e}\gamma$  where h is Planck's constant, e is magnitude of electron charge,  $\gamma$  is the phase difference of the superconducting order parameter across the junction [5].

<sup>&</sup>lt;sup>1</sup>Note that in most lumped circuit models of the Josephson junction, the nonlinear inductor is usually represented by a pair of triangles [3]. However, the correct symbol that should be used is that of a nonlinear inductor.

The normalized circuit equations are Eqs.(1) through (3)

$$\dot{\phi} = v \tag{1}$$

$$\dot{v} = \frac{1}{C} \left( i - G \cos(k_0 \phi) v - I_0 \sin(\phi) - i_x \right)$$
(2)

$$\dot{i_x} = \frac{1}{L^*} \left( v - i_x R \right)$$
 (3)

The model above was obtained from considering the microscopic theory of Josephson junctions [4]. In Josephson's original papers dealing with thin-film junctions, the coefficients G,  $k_0$  and  $I_0$  in Eq.(2) are dependent on junction voltage [4]. However, this dependence may be neglected provided the voltage stays small when compared to the energy-gap voltage of the individual superconductors [1] Josephson mentions that the cos term in Eq.(2) contributes to damping effects. Although a similar circuit model was proposed in [2], the shunt inductive branch is not included.

A phase-plot of the simulated attractor obtained from Eqs.(1) through (3) is shown in Fig 2.

## References

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Figure 2: Plot of  $(v(t), i_x(t))$ . Initial conditions are  $\phi(0) = 0, v(0) = 1.25, i_x(0) = 1.4$ . Parameters are  $C = 1, i = 1, G = 1, k_0 = 2, I_0 = 1, L = 8, R = 1$ . Simulation was carried out for 10000 steps using an explicit Euler method in Mathematica 8.